

EPSil Steering System in the Loop





Agenda



Introduction

- What can you do with EPSiL?
- Key performances of EPSiL
- Versions
- Virtual Column
- Steering Motor Cube
- Customization



Introducing EPSiL: Real-Time test bench for Steering Systems.

EPSiL enables real-time testing of complete steering systems in indoor settings. Designed to analyze the interaction between wheel forces, steering functions, and human interaction, EPSiL ensures comprehensive evaluations.

EPSiL applies steering link forces respecting vehicle kinematics, while allowing drivers to handle the steering wheel and interact with virtual simulations and drive virtual cars with real steering system.







DUT's EPS system



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What can you do with EPSiL?

EPSiL Bench provides a suitable platform for the development, fine-tuning, and validation of steering functions within controlled environments.











FuSa - Fault injection

SOTIF **Management of predictable** risks



Subjective Evaluations
Steering feel



Key performances of EPSiL

EPSiL is designed for easy integration and precise performance. With real-time testing capabilities and accurate reproduction of steering system working conditions, EPSiL ensures reliable results.





Communication latency





Communication protocol with the real-time machine



Max dynamic force on the steering link 20 kN



Max linear travel of robotized pedal





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EPSiL versions

EPSiL fully integrates steering system components into simulation loop. With a rocker-link mechanism, EPSiL applies forces in three spatial directions, not just in line with the rack, just like it happens in a real car.

Choose between vertical- or horizontal-oriented motors to tailor EPSiL to your specific steering system testing needs.





Vertical motors



Steering Motor Cube - Not only a support for Steering Robot

Steering Motor Cube ensures precise positioning of the steering column in line with the real car, allowing the SR position to be adjusted in three directions and in pitch too.

With SMC, you can both control your EPSiL bench from a remotized cockpit and perform automated testing.

Furthermore, you can use SMC as a steering wheel actuator in a Steer-by-Wire system test bench, decoupling it's application from the only use on EPSiL bench.





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Virtual Column - Steering wheel and steering column united, even remotely

Virtual Column provide the possibility to drive your EPSiL bench also from a remoted cockpit with the use of the FS (Feedback System) and SR (Steering Robot) actuators.

The FS actuator provides an incredibly realistic steering feedback based on the actual dynamics of the DUT in EPSiL, that is controlled by SR. The future-enabling

The future-enabling answe





EPSiL can be a built-onyou product

Imagine a product that feels like it was made just for you - because it was.





What can you custom on your EPSiL?

Rocker links geometry and dimensions

DUT central frame and motor island links

Connectors/wiring

Tuning controls and interfaces



Brake System in the Loop





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Introducing BrakeiL: real-time rig for testing complete brake systems.

The brake pressure is directly built up by the master cylinder and all the braking functions (ABS, ESC, etc.) are physically performed by the devices under test.

With BrakeiL you can test complete brake system including (depending on the vehicle under test):



Brake pedal

Master cylinder

Brake-By-Wire



One-box brake system







Brake booster (pneumatic, electric, electromechanical, etc.)

Hoses, callipers, pads, and discs



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What can you do with BrakeiL?

BrakeiL enables human-driven and automated tests into driving simulators and it is suitable to develop, tune and validate braking functions in:











FuSa Fault injection



Subjective Evaluations
Brake pedal feel

Vehicle Dynamics ABS/ESC



Key performances of BrakeiL

BrakeiL is designed for easy integration and precise performance. With real-time testing capabilities and accurate reproduction of wheel speed signals, BrakeiL ensures reliable results.





Communication latency < 3 ms

Max force of robotized pedal 2000 N



Max linear velocity of robotized pedal 1.1 m/s



Max linear travel of robotized pedal 150 mm



Communication protocol with the real time machine **EtherCAT**



BrakeiL versions

BrakeiL integrates brake system components into simulation loops. In its standard version, the driver has the option of acting on the brake system from the cockpit. In its remoted version, on the other hand, BrakeiL also allows the bench to be mounted in a location other than the cockpit, enabling the braking system to be controlled remotely.







BrakeiL - REM



BrakeiL optionals

Complete your BrakeiL bench with our products: you can use the bench with all its functions.

WSE – Wheel Speed Emulator





Valve systems for adjusting system compliance



BrakeiL options



Compatible with disc and drum systems





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BrakeiL can be a builton-you product

Imagine a product that feels like it was made just for you because it was.

BrakeiL can be a builton-you product







Camil Camera in the Loop





Agenda



Introduction

Keys performances of CamiL

03

What can you do with CamiL?





Customization

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Introducing CamiL: Bridging the Gap Between Real-World and Simulation Environments!

Unlock the power of camera-based vehicle functions in your driving simulator lab with CamiL. Integrating virtual scenarios into your setup, CamiL immerses your camera in lifelike simulations through an advanced system of lenses and monitors.

But that's not all – CamiL goes beyond visuals. With virtual sensors complementing your suite of sensing devices, experience the full spectrum of ADAS functionalities in action.





What can you do with CamiL?

CamiL enables to test all the functionalities of the vehicle's vision devices in a controlled environment.









FuSa Fault injection



Key features of CamiL

CamiL allows the introduction of the camera-based vehicle functions into a driving simulator laboratory.





Fully adjustable camera position **x, y, z and pitch angle**





Communication protocol with the real time machine CAN, Flexray, others



CamiL options

Bench offers the option to integrate our advanced blinding system. This enhancement allows CamiL to realistically replicate various scenarios, accurately simulating the effects of sudden flashes of light on camera performance.



Blinding system



CamiL can be a built-on-you product

Imagine a product that feels like it was made just for you -because it was.









What can you custom on your CamiL?

Camera adjustable linkages to CamiL

Camera field adaptation lens

Connectors/Tuning controls and interfaces



WSE Wheel Speed Emulator





Agenda



Introduction





Introducing WSE:

this device estabilished the raw signals of up to four wheel speed sensor into HIL simulations.

Supply Voltage



Communication rate Up to 100 Mbps (EtherCAT) / 1 Mbps (CAN)

Communication EtherCAT or CAN

What can you customize?

- •Tunable wheel Parameters (Radius, pole number)
- •User defined data protocol bits
- •Switching protocol
- •AK protocol



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FB Passive Feedback Unit

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Introduction

Customization

04

03

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Introducing FB: Customizable Pedal Feel for Brake-by-Wire Vehicles.

FB is a compact and lightweight device designed to tailor pedal feel to individual preferences in brake-by-wire vehicles. Its friction-minimizing technology ensures precise responsiveness, adapting smoothly to user needs.

Plus, FB seamlessly integrates with our simulators, enhancing the cockpit experience with adjustable pedal feel.

Key performances of FB

Discover the most brilliant features of FB.

The futureenabling answer

(+39) 055 628 3216

info@meccanica42.com

www.meccanica42.com

